

2D tilted-ring fitting of disk galaxies in large HI galaxy surveys

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with

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- An overview of WALLABY kinematics pipeline
- A new Bayesian MCMC 2D tilted-ring fitter
- Performance test (model & observed galaxies)
- Summary & future works

ASKAP WALLABY (Koribalski & Staveley-Smith)

WALLABY

- ASKAP 3n HI galaxy survey
- ~5,000 hours of ASKAP time
- ~500,000 galaxies out to $z \sim 0.26$

→ ~6,000 galaxies within 200 Mpc, spatially resolved by > 6 beams (Duffy et al. 2012)

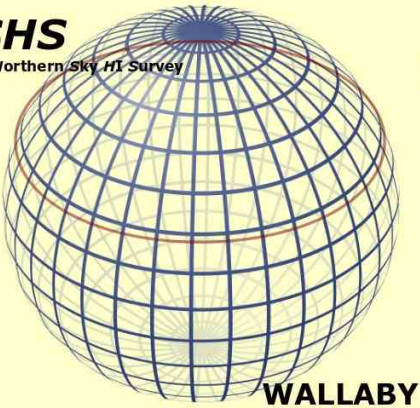


WSRT Apertif WNSHS (Gozsa et al.)

WNSHS

Westerbork Northern Sky HI Survey

1 π



- The Westerbork Northern Sky 1 π HI Survey (WNSHS) with the WSRT Apertif

- ~1400 pointings of the sky ($\delta > +27$ deg) with 15''~30'' angular resolution

- WALLABY-like channel resolution (0.1 MHz), number (16,384) and rms sensitivity (~0.6 mJy/beam)

- Redshift range of 0 ~ 0.26

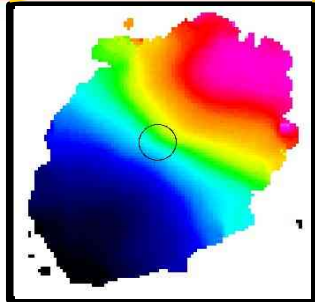
→ If combined with WALLABY, the expected number of galaxies for resolved kinematics is >13,000

: Mass distribution in galaxies, interplay between ISM and star formation on (sub-) kpc scales, dynamical morphology and structure (bars, warps, spiral arms, tidal interaction etc.), angular momentum etc.

→ How to do source characterisation and parameterisation?

Automated kinematic parameterisation

ASKAP WALLABY/DINGO (~6,000) + WSRT WNSHS (~7,000)

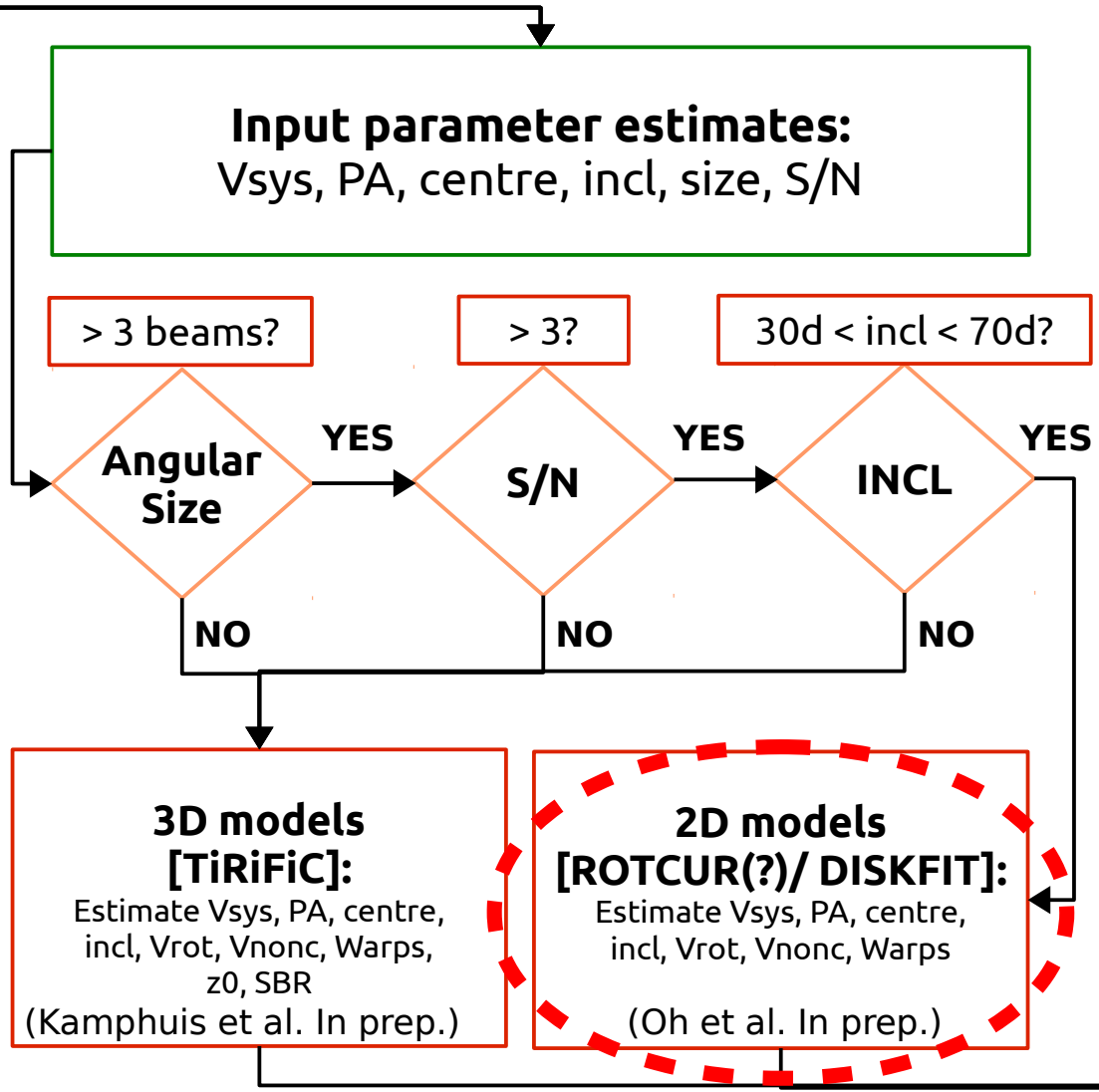


2D velocity field

Moment 0 & 2

Ancillary data

3D Data cube

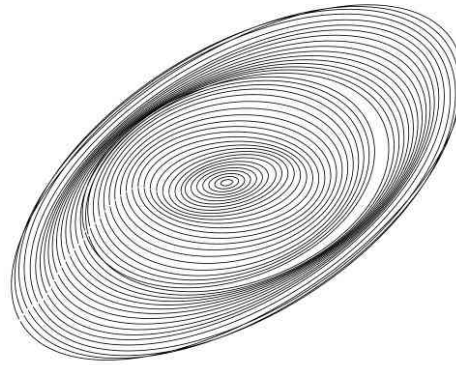
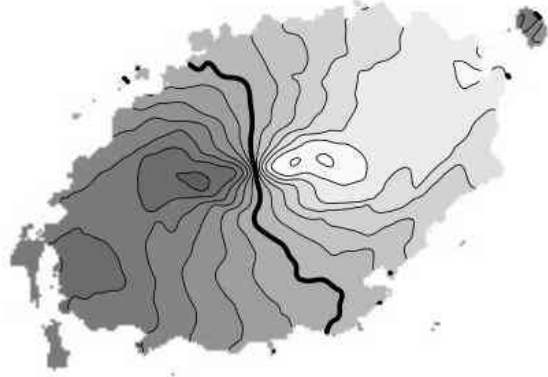


I. WALLABY resolved source catalog: Vsys, PA, incl, ang. Size, S/N, centre, Vrot, uncertainties, warp, z0, SBR etc.

II. WALLABY data products: model cube, moment maps, bulk & nonc. maps, ancillary data etc.

2D tilted-ring model (Rogstad et al. 1974)

NGC 5055 (Battaglia et al. 2005)



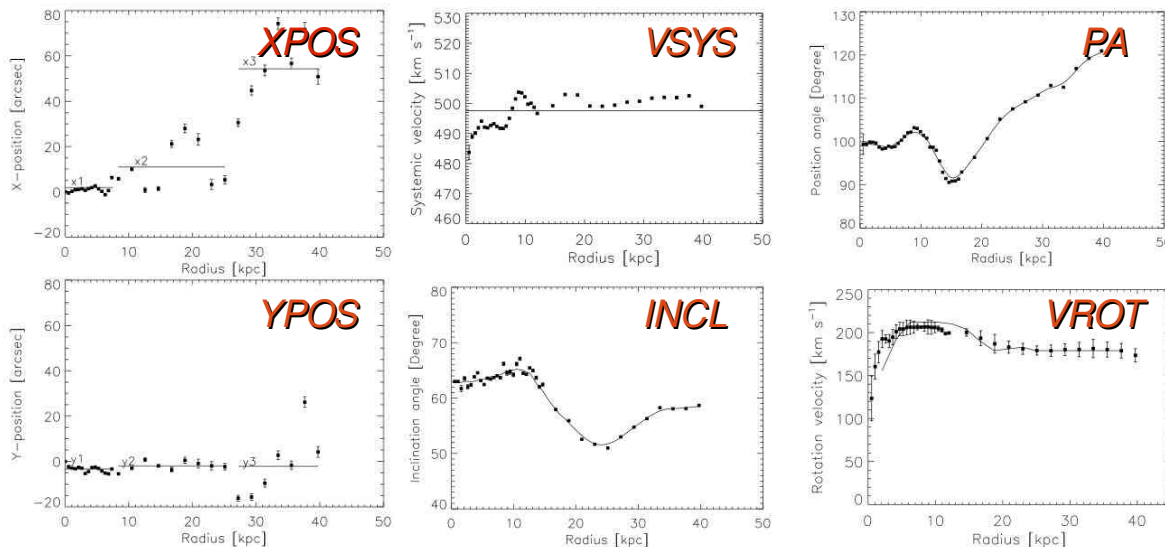
Free: **XPOS, YPOS, VSYS, PA, INCL, VROT**
Fixed: **VEXP**

Free: **PA, INCL, VROT**
Fixed: **XPOS, YPOS, VSYS, VEXP**

Free: **XPOS, YPOS, VROT**
Fixed: **VSYS, VEXP, PA, INCL**

Free: **VROT**
Fixed: **XPOS, YPOS, VSYS, VEXP, PA, INCL**

Derive the final rotation curve



Galaxy Radius

Galaxy Radius

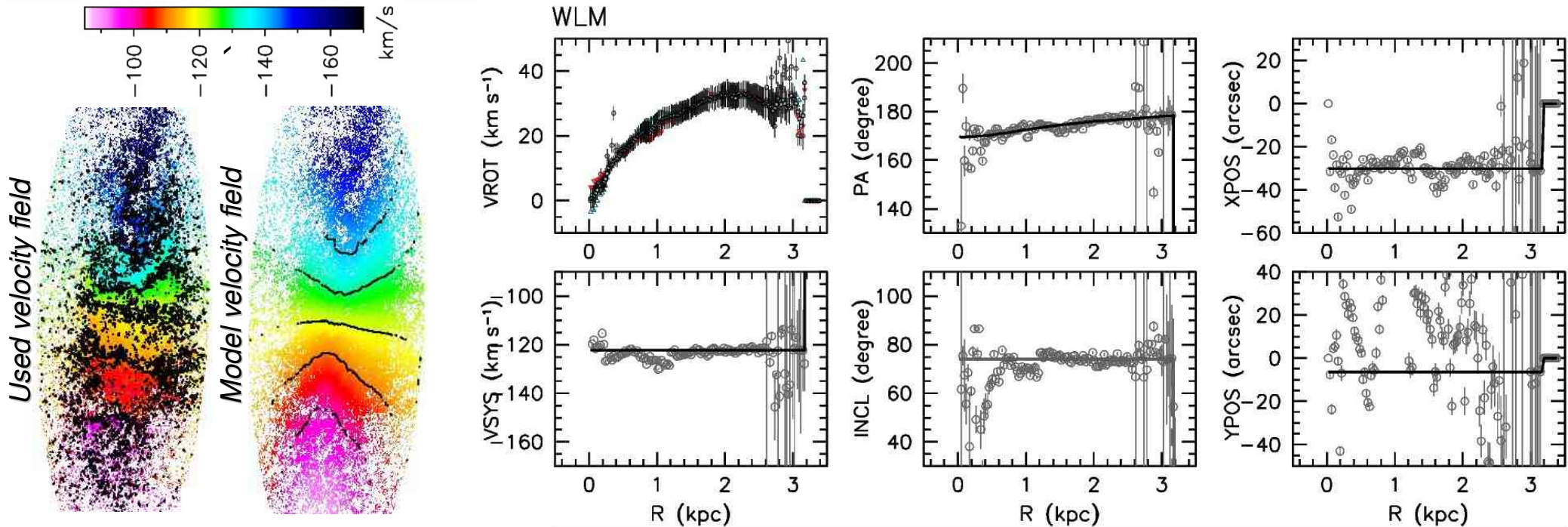
Galaxy Radius

$$V_{\text{obs}}(x, y) = V_{\text{sys}}(x, y) + \sin i \{ V_t(x, y) \cos \theta + V_r(x, y) \sin \theta \}$$

$$\cos \theta = \frac{-(x - \text{XPOS}) \sin(\text{PA}) + (y - \text{YPOS}) \cos(\text{PA})}{r}$$

$$\sin \theta = \frac{-(x - \text{XPOS}) \cos(\text{PA}) - (y - \text{YPOS}) \sin(\text{PA})}{r \cos(\text{INCL})}$$

Some issues on 2D tilted-ring fits



- 6 free parameters
- VROT/INCL degenerated
- ***sensitive to initial estimates***
- ***non-parametric PA /INCL models***
- affected by non-circular motions



→ ***difficult to make the fit automated***

→ **Why don't we fitting a 2D model to the velocity field at one time rather than dividing it into tilted-rings?**

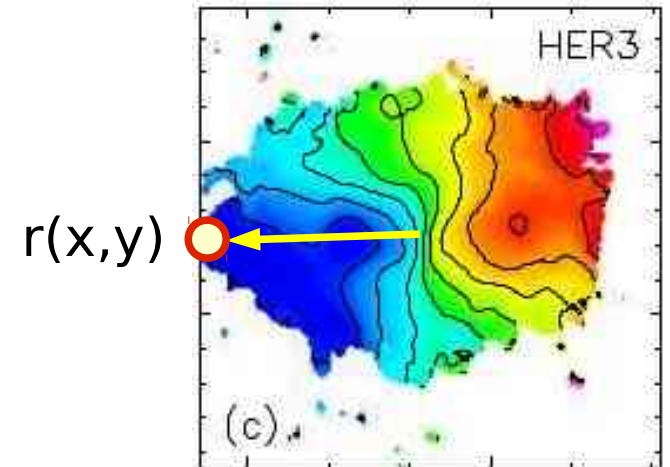
2D tilted-ring model

$$V_{MODEL}(x, y) = V_{SYS}(x, y) + \underline{V_{ROT}(r)} \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$\cos \theta = \frac{-(x - XPOS) \times \sin PA + (y - YPOS) \times \cos PA}{r}$$

$$\sin \theta = \frac{-(x - XPOS) \times \cos PA - (y - YPOS) \times \sin PA}{r \cos I}$$

$$\underline{r} = \sqrt{\left[-(x - XPOS) \times \sin \theta + (y - YPOS) \times \cos PA \right]^2 + \left[\frac{(x - XPOS) \times \cos PA + (y - YPOS) \times \sin PA}{\cos I} \right]^2}$$



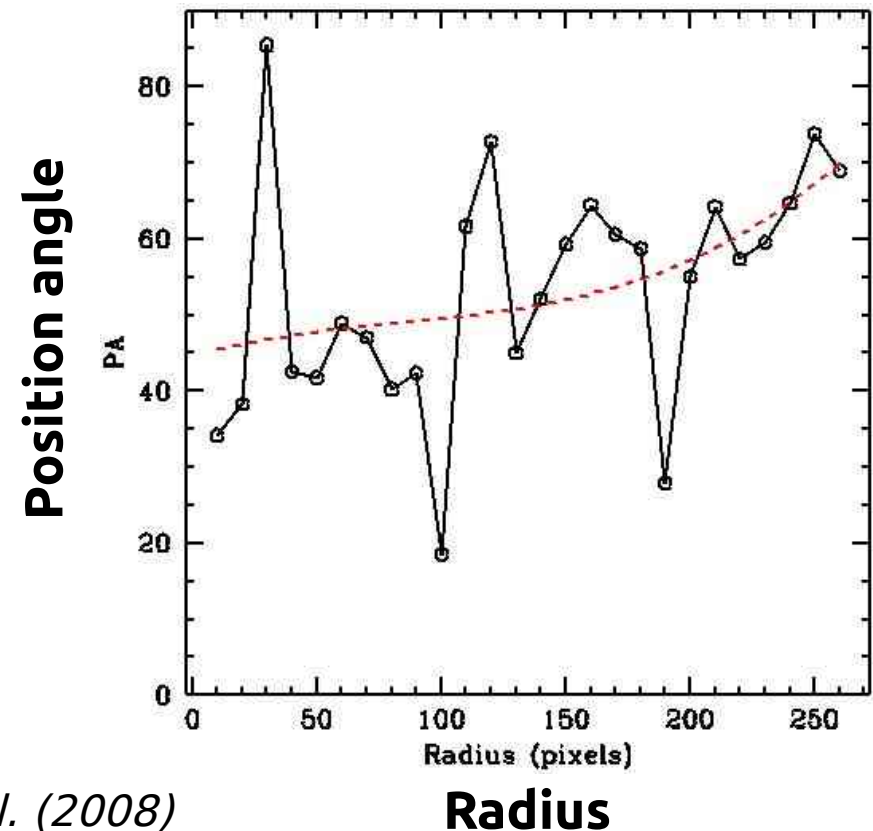
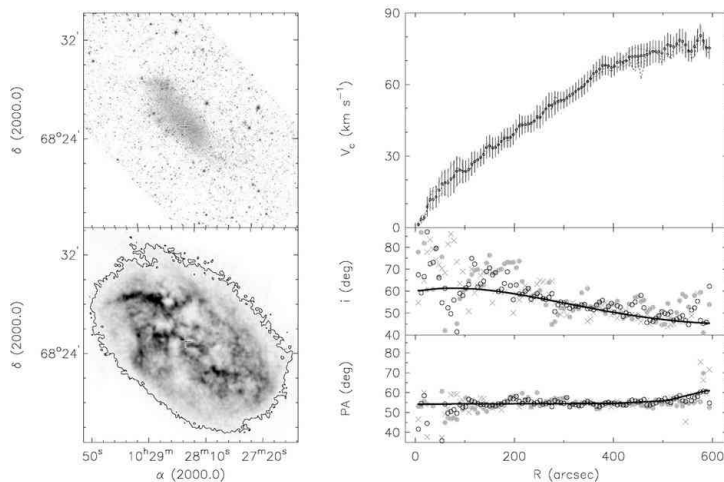
: If PA and INCL vary with galaxy radius (not constant), the galaxy radius can be derived in an iterative way by solving the above equation with given functional forms of $PA(r)$ and $INCL(r)$

Kinematic position angle

- Kinematic PA often varies with galaxy radius due to dynamical structures in galaxies (e.g., lopsideness, bar-like potential, spiral arms, non-circular motions etc.)
- Kinematic PA can be modelled by polynomials or Fourier series

$$PA(r) = \sum_{n=0}^m p_n r^n$$

$$PA(r) = \sum_{n=0}^m [a_n \cos(nwr) + b_n \sin(nwr)]$$



de Blok et al. (2008)

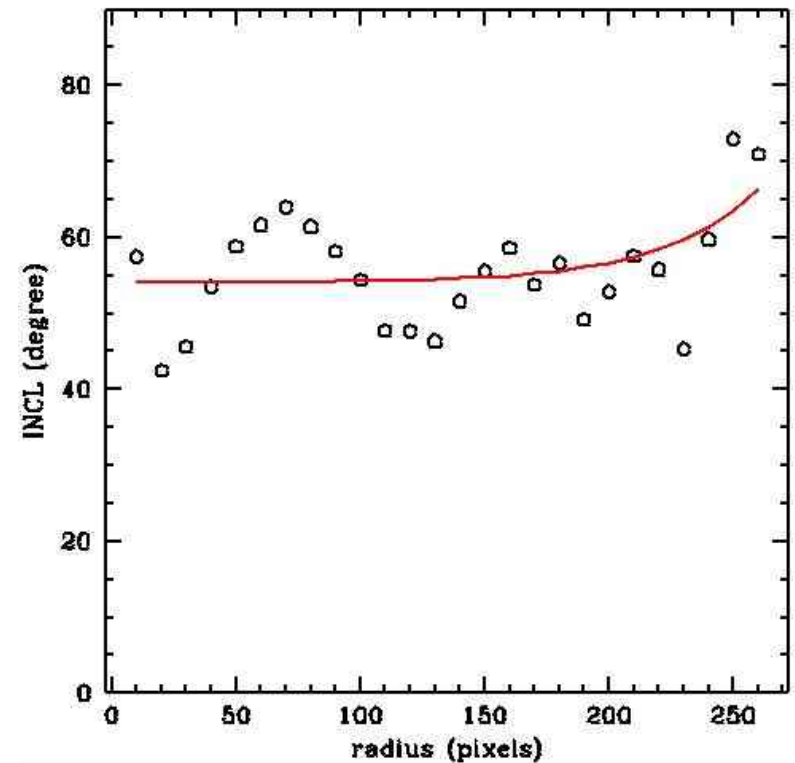
Kinematic inclination

- Kinematic INCL often varies with galaxy radius, particularly in the outer region where warps may exist
- A modified Sersic profile or Fourier series can be used for taking such radial variation into account

$$INCL(r) = \sum_{n=0}^m i_n r^n + \kappa \exp\left(\frac{r^\beta}{\alpha}\right)$$

$$INCL(r) = \sum_{n=0}^m [a_n \cos(nwr) + b_n \sin(nwr)]$$

Inclination



Radius

2D tilted-ring model

$$V_{MODEL}(x, y) = V_{SYS}(x, y) + \underline{V_{ROT}(r)} \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$\cos \theta = \frac{-(x - XPOS) \times \sin PA + (y - YPOS) \times \cos PA}{r}$$

$$PA = PA(r, a_n, b_n, w || r, p_n)$$

$$\sin \theta = \frac{-(x - XPOS) \times \cos PA - (y - YPOS) \times \sin PA}{r \cos I}$$

$$INCL = INCL(r, a_n, b_n, w || r, i_n, \kappa, \alpha, \beta)$$

$$r = \sqrt{\left[-(x - XPOS) \times \sin \underline{PA} + (y - YPOS) \times \cos \underline{PA} \right]^2 + \left[\frac{(x - XPOS) \times \cos \underline{PA} + (y - YPOS) \times \sin \underline{PA}}{\cos I} \right]^2}$$

→ $r = r(x, y, XPOS, YPOS, PA(a_n, b_n, w || p_n), INCL(a_n, b_n, w || i_n, \kappa, \alpha, \beta))$

→ Solve this non-linear equation and derive the galaxy radius, r in the galaxy plane with given kinematic center ($XPOS$, $YPOS$), PA and $INCL$ at sky coordinates (x, y) (e.g., Newton-Rapson method etc.)

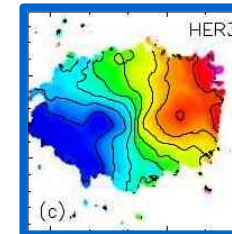
2D tilted-ring model

$$V_{MODEL}(x, y) = V_{SYS}(x, y) + V_{ROT}(r) \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$r = r(x, y, XPOS, YPOS, PA(a_n, b_n, w || p_n), INCL(a_n, b_n, w || i_n, \kappa, \alpha, \beta))$$

$$V_{ISO}(r) = \sqrt{4\pi G \rho_0 r_c^2 \left[1 - \frac{r_c}{r} \arctan\left(\frac{r}{r_c}\right)\right]} \quad (\text{e.g., Pseudo-isothermal halo model rotation curve})$$

$$\rightarrow V_{model} = V(XPOS, YPOS, V_{SYS}, V_{EXP}, \overbrace{PA(a_n, b_n, w || p_n)}^{PA}, \overbrace{INCL(a_n, b_n, w || i_n, \kappa, \alpha, \beta)}^{INCL}, \overbrace{V_{rot}(r_c, \rho_0)}^{VROT})$$

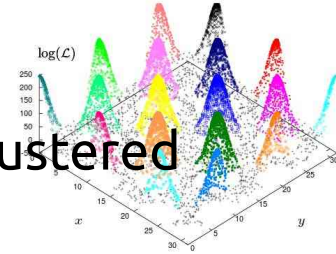


$$\log L = -\frac{N}{2} \log 2\pi - \sum_{i=0}^{NAX1} \sum_{j=0}^{NAX2} \log \sigma_{ij} - \frac{1}{2} \sum_{i=0}^{NAX1} \sum_{j=0}^{NAX2} \left[\frac{V_{obs}(i, j) - V_{MODEL}(i, j)}{\sigma_{ij}} \right]^2$$

Likelihood

MultiNest (Feroz & Bridges 2007, 2008) : a Bayesian inference tool

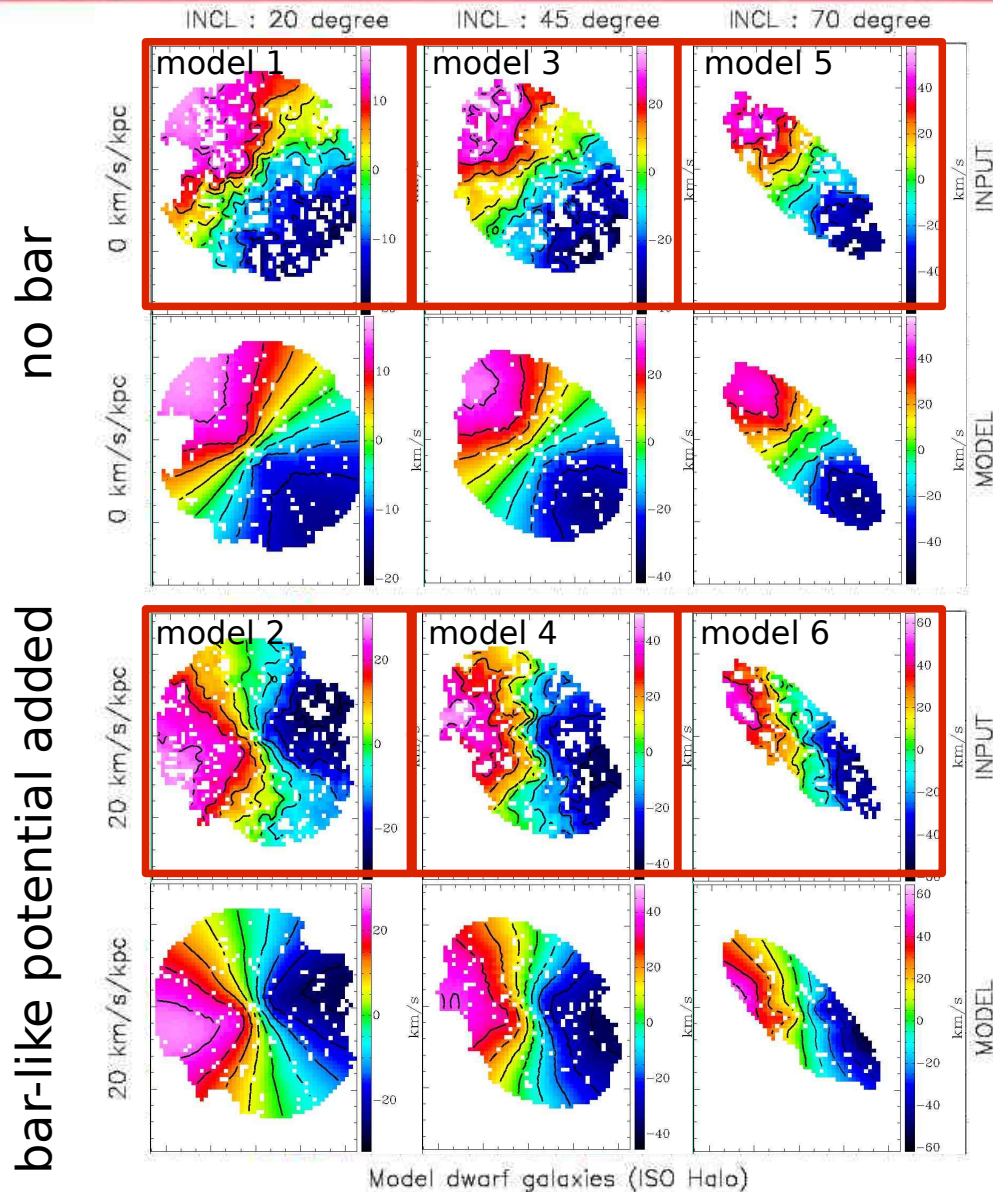
- Improves the sampling efficiency and robustness based on the clustered nested sampling in Shaw et al. (2007)
- Calculates the evidence and explores parameter space even with multimodals and curving degeneracy in high dimensions
- Refer to Feroz & Bridges (2008) for a complete discussion on the new sampling scheme, “the improved simultaneous ellipsoidal nested sampling method”
 - a fully parallelized algorithm using MPI
- Successfully implemented in astrophysics and cosmology (e.g., CosmoMC, SuperBayeS, SUSY, gravitational lensing, exo-planet detection, **ASKAP FLASH absorption line finder** (Allison et al. 2012))



- Standalone C program for 2D tilted-ring fitting based on Bayesian MCMC
 - MultiNest v3.7, CFITSIO, GNU & standard ANSI C libraries
 - **fully automated**: estimation for initial priors, convergence check and derivation of the final rotation curve for a given 2D velocity field
 - less sensitive to initial estimates and good error estimation
 - **several builtin rotation curve shape functions** (e.g., pseudo-isothermal, Burkert, polynomial rotation curves etc.)
 - the larger number of sampling, the higher quality of fits but the more cpu time required
- Message Passing Interface (MPI) for **parallel computing**

Performance test

I. model velocity fields

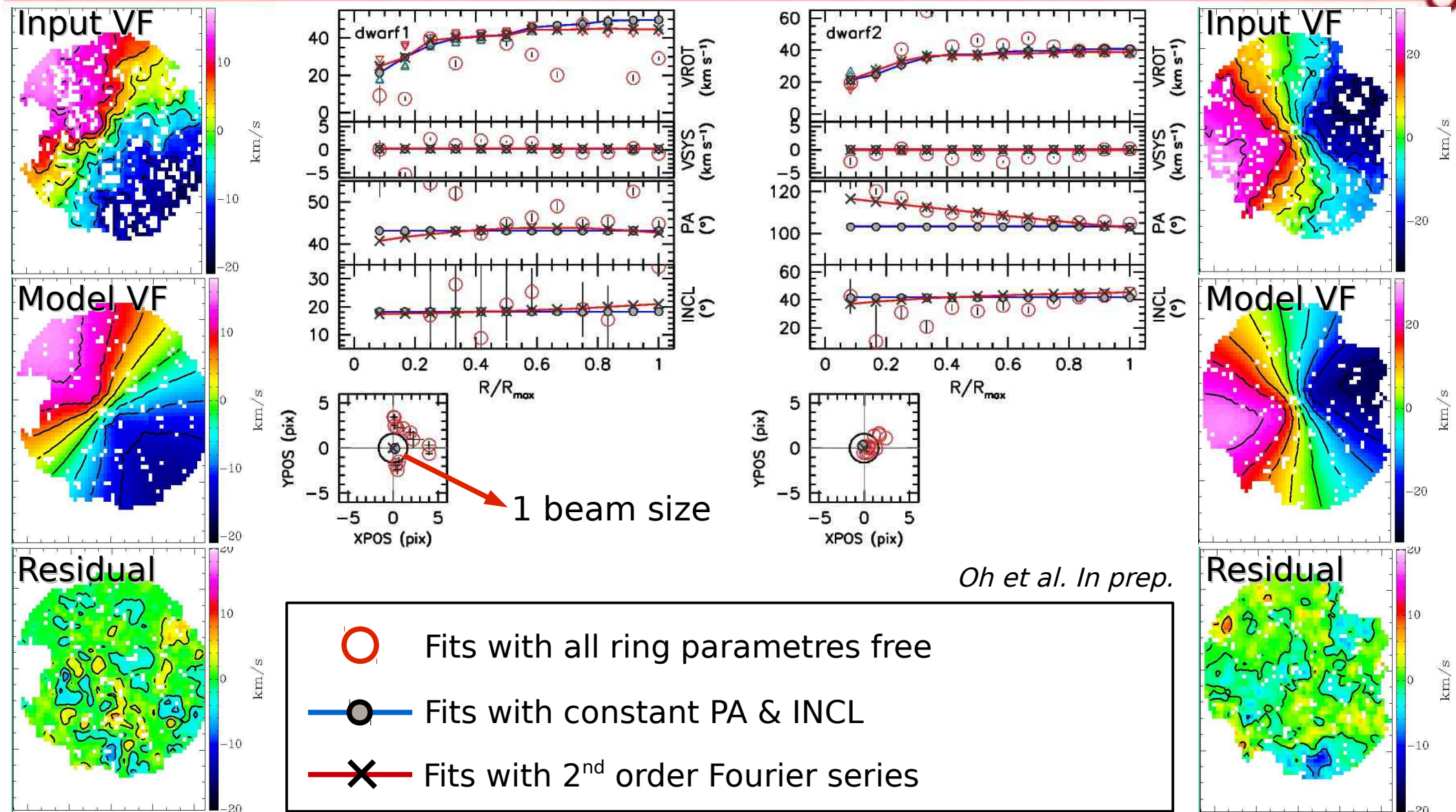


- Construct model data cubes based on galaxy properties from THINGS (e.g., HI column density, HI velocity dispersion, rotation curves etc.)
- Add small-scale random & large-scale bar-like non-circular motions
- Smooth the cubes with 24" beam
- Re-observe the cubes at 20, 45 & 70 degrees viewing angles
- Extract 2D velocity fields

Performance test

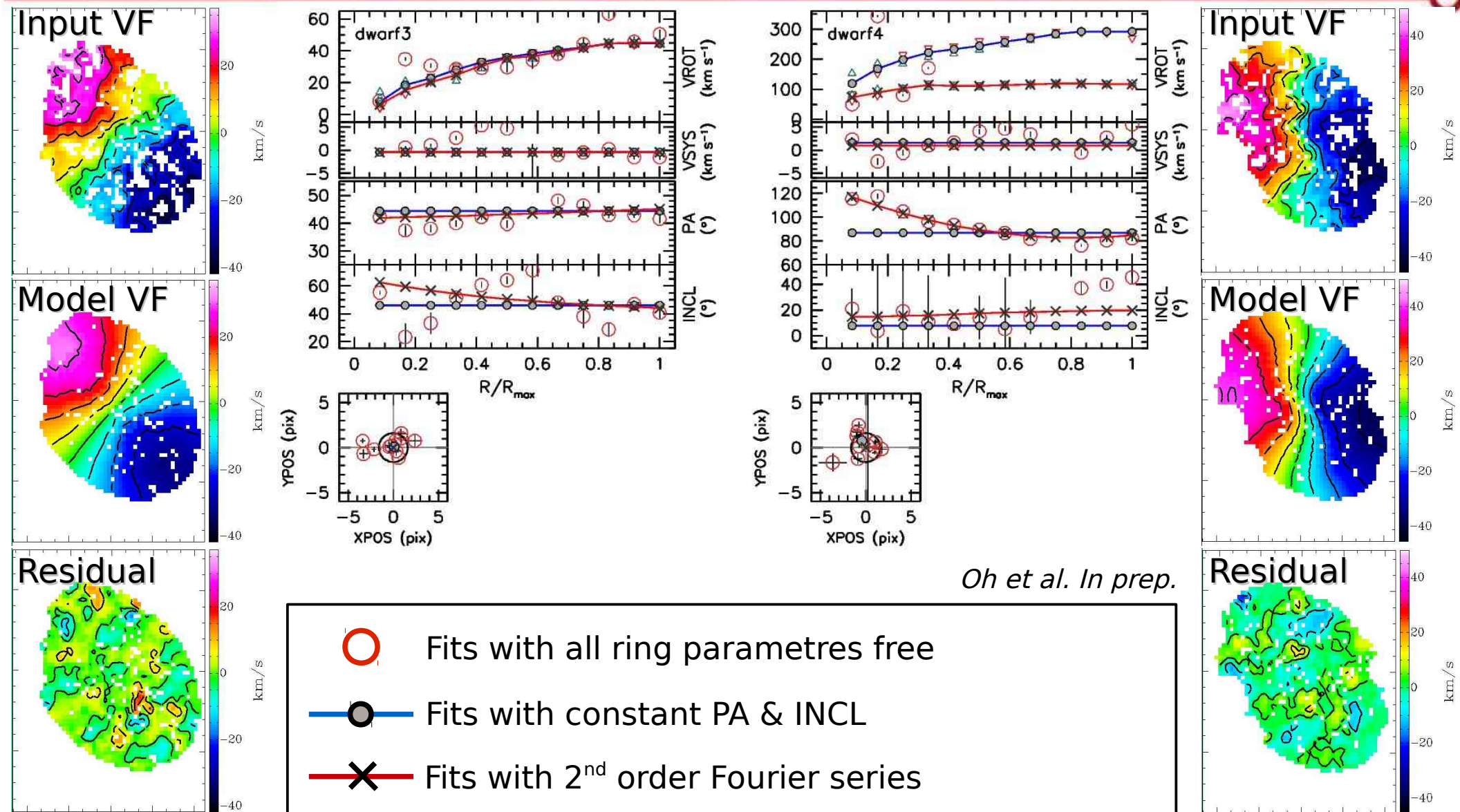
Model 1 : 20° inclination + no bar

Model 2 : 20° inclination + bar



Performance test

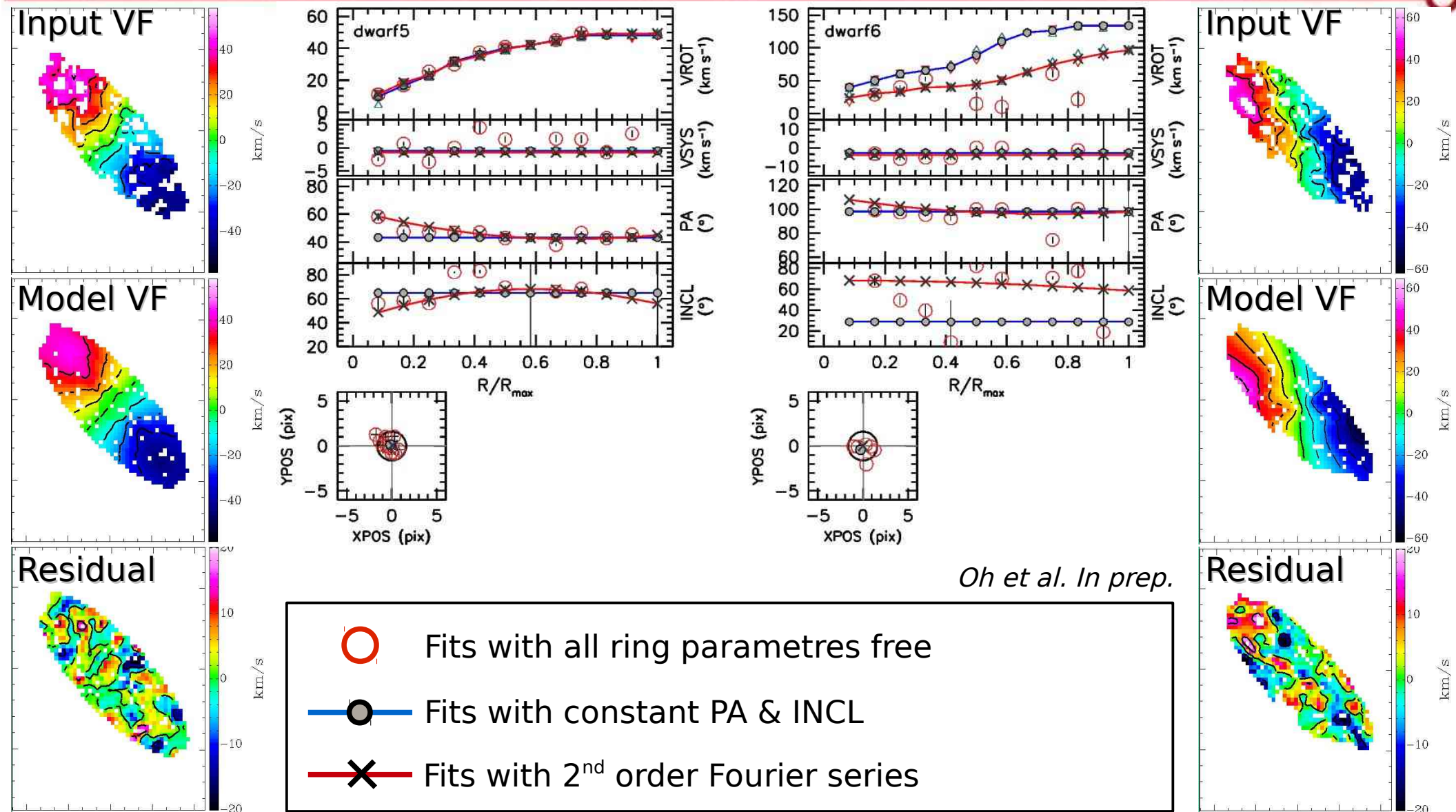
Model 3 : 45° inclination + no bar
Model 4 : 45° inclination + bar



Oh et al. In prep.

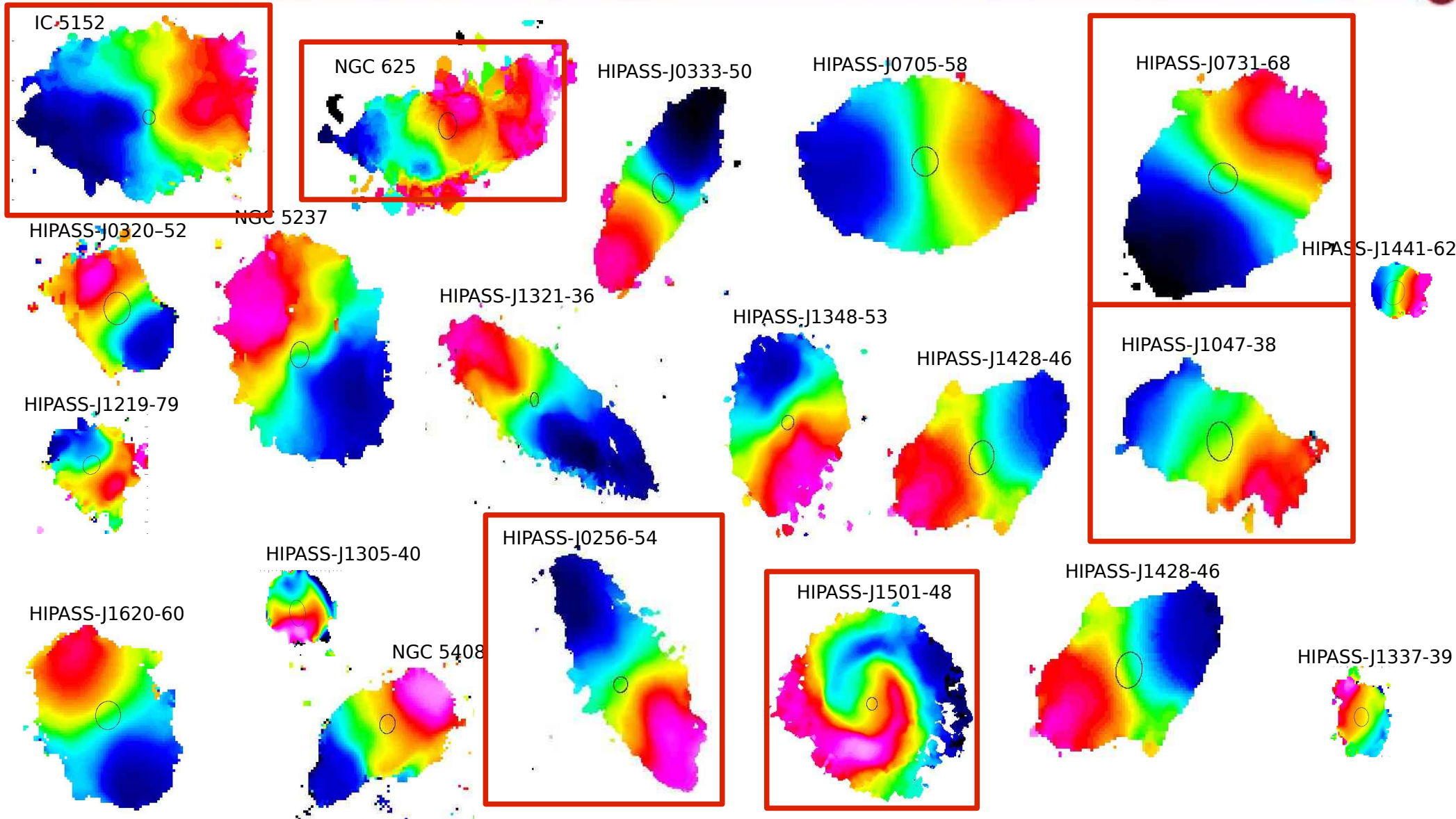
Performance test

Model 5 : 70° inclination + no bar
Model 6 : 70° inclination + bar

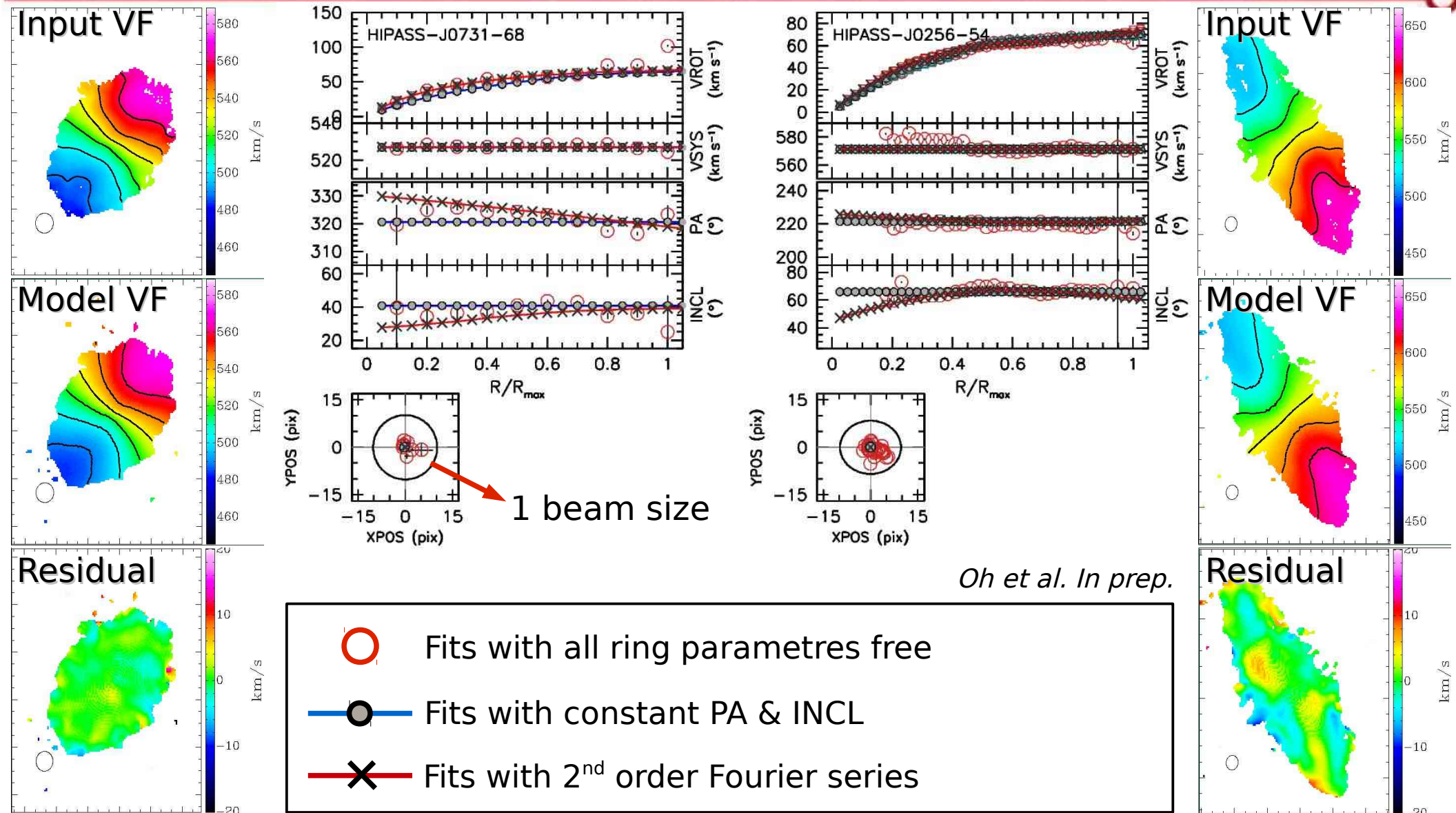


Performance test

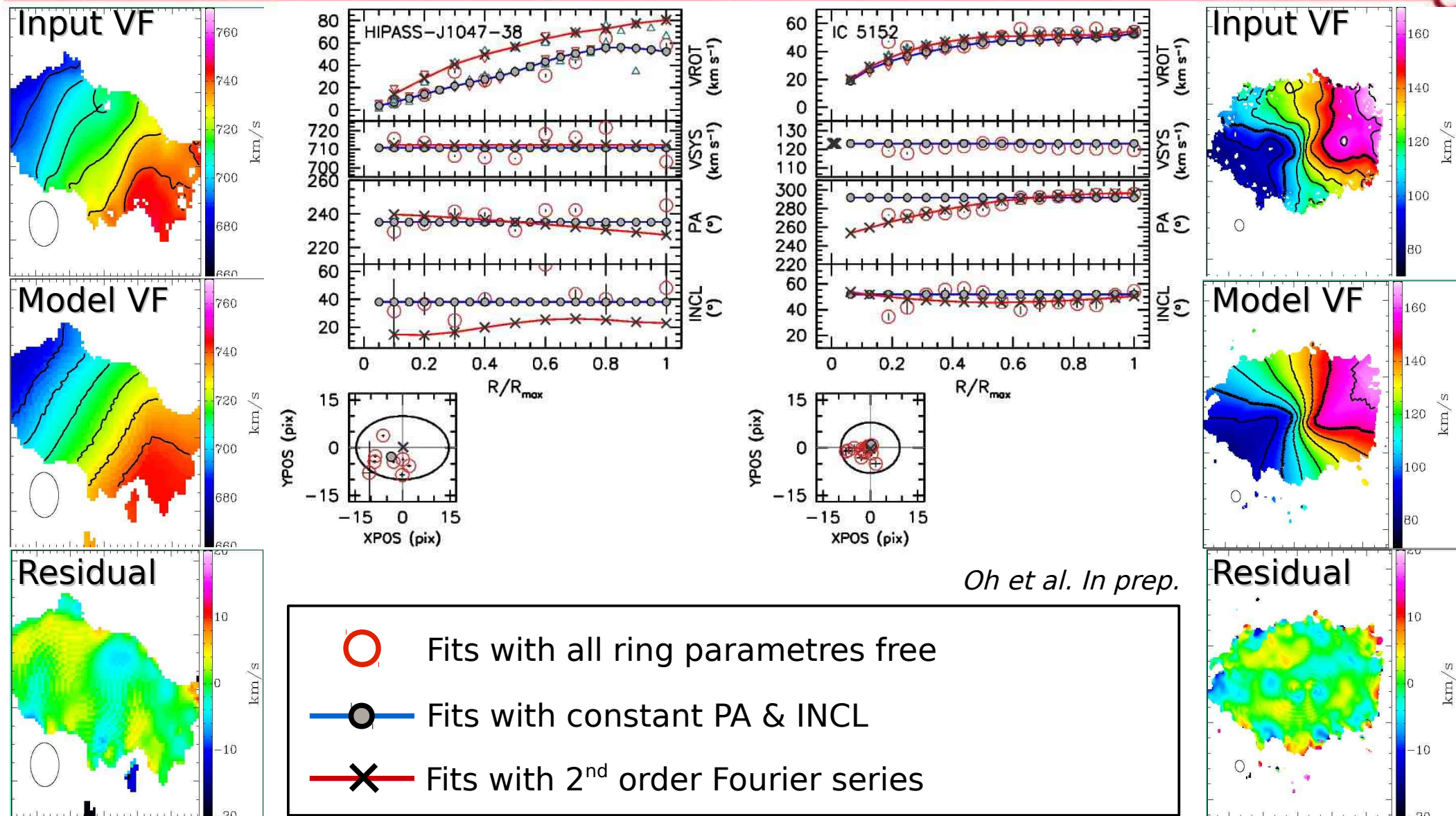
II. Local Volume HI Survey (LVHIS; Koribalski et al.)



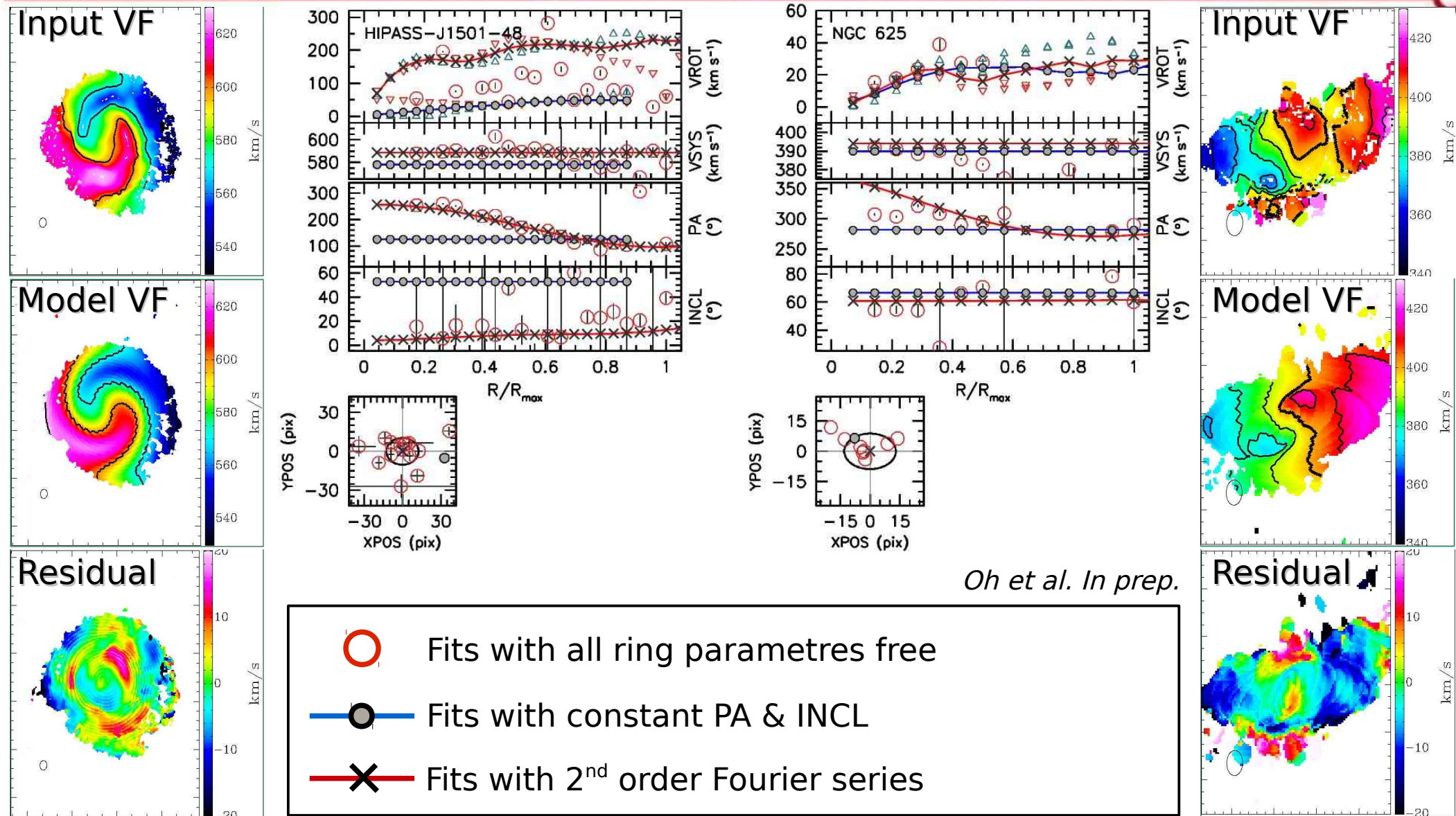
Performance test: : LVHIS sample galaxies



Performance test : LVHIS sample galaxies



Performance test : LVHIS sample galaxies



Oh et al. In prep.

Summary & future direction

- **A new 2D tilted-ring fitting algorithm** based on Bayesian MCMC developed
- **A standalone C program employing MultiNest** (a Bayesian inference tool) developed:
 - **fully automated**: broadly defined ranges of priors of the parameters are only required for a given 2D velocity field; provide good fit results comparable to those derived using standard tilted-ring fitting code even without exhaustive manual iterations
 - **MPI supported**: written in MPI for the parallel implementation of MultiNest either on a multi-core single (tested) or a cluster system (will be tested using Pleiades, a cluster machine at ICRAR)
- **Successfully tested using WALLABY-like 13 LVHIS sample galaxies as well as numerous model velocity fields (extended test using THINGS + LITTLE THINGS sample galaxies)**
- (Will) estimate optimal initial priors, derive rotation curves and visualise the results of **> 10,000 resolved galaxies from ASKAP WALLABY/DINGO + WSRT WNSHS (+ also useful for MeerKAT MHONGOOSE)**
- **Also applicable to velocity fields from IFU observations** (e.g., SAMI, MANGA etc.)
- Implications: e.g., **statistical revisit of HI rotation curve** of galaxies from all available literature data (rotation curve shape, cusp/core, etc.)
- Will be publicly available after the internal release to team members (stay tuned...)